

# On Taylor Model Methods for Solving Linear ODEs with Constant Coefficients

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# Introduction

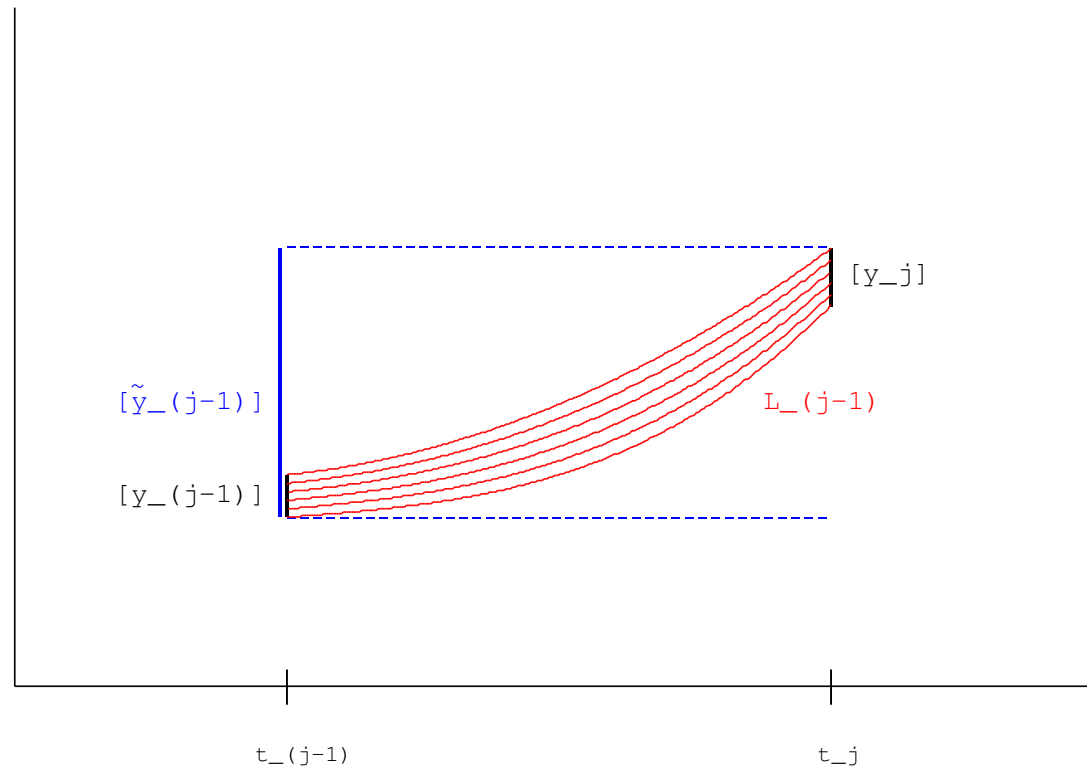
IVP:

$$y' = B y$$
$$y(0) = y_0 = c_0 + C_0 x \quad ( y(0) = y_0 \in [y_0] ),$$

where

- $B$ :  $(n, n)$ -matrix,
- $c_0$ :  $n$ -vector,
- $C_0$ :  $(n, n)$ -diagonal matrix
- $x$ : symbolic  $n$ -vector with components  $x_i \in [-1, 1]$ .

# Direct Interval Method



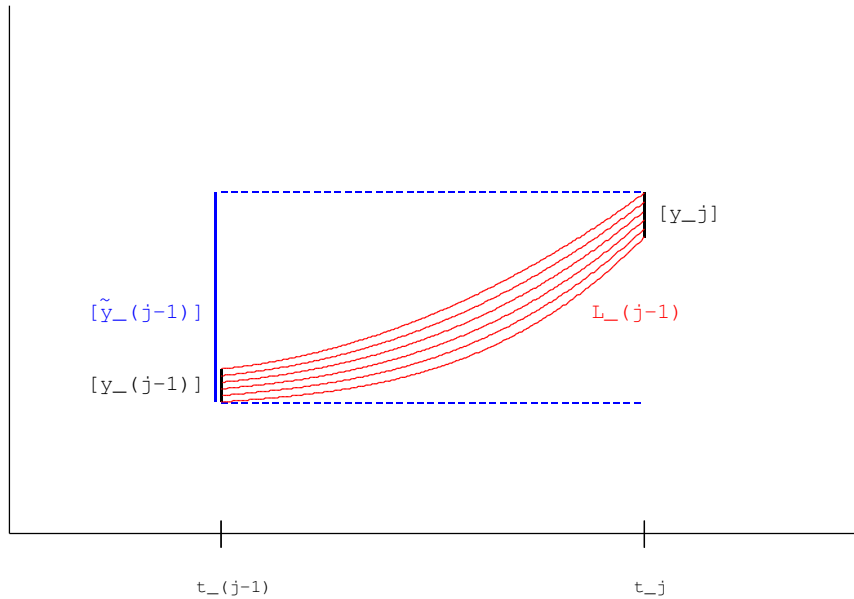
$$t_j := t_{j-1} + h, \quad j = 1, 2, \dots$$

$$L_{j-1} := \{u(t) \mid u' = Bu, u(t_{j-1}) = y_{j-1} \in [y_{j-1}], t \in [t_{j-1}, t_j]\}.$$

$[\tilde{y}_{j-1}] \in \mathbb{I}\mathbb{R}^n$  : a priori enclosure such that  $\forall y \in L_{j-1}$  :

$$y(t) \in [\tilde{y}_{j-1}] \quad \text{for all } t \in [t_{j-1}, t_j].$$

# Direct Interval Method



$$y(t_j) = Ty(t_{j-1}) + \tilde{z}_j,$$

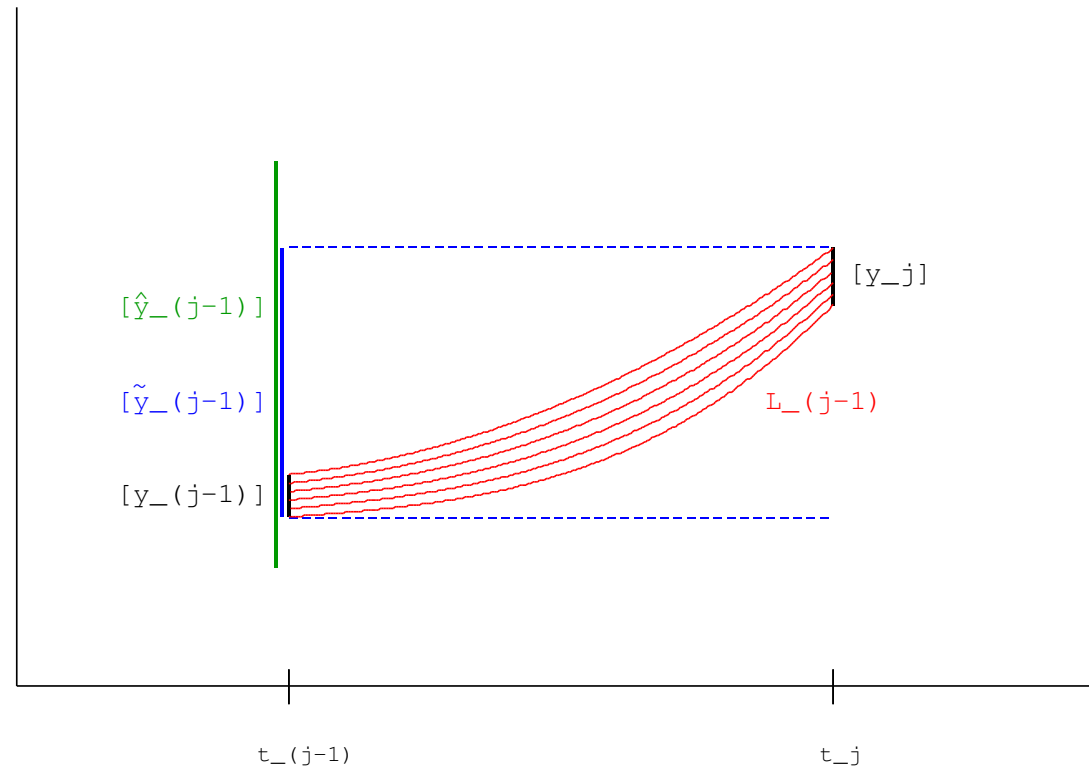
where

$$T := \sum_{i=0}^k \frac{(hB)^i}{i!}, \quad \tilde{z}_j \in [z_j] := \frac{(hB)^{k+1}}{(k+1)!} [\tilde{y}_{j-1}].$$

Direct interval method:

$$[y_j] := T[y_{j-1}] + \frac{(hB)^{k+1}}{(k+1)!} [\tilde{y}_{j-1}], \quad j = 1, 2, \dots$$

# Coarse Enclosure



Fixed point iteration: Determine  $[\hat{y}_{j-1}]$  such that

$$[y_{j-1}] + [0, h] B [\hat{y}_{j-1}] \subseteq [\hat{y}_{j-1}].$$

# TM Method: Explicit Example

IVP: 
$$y' = B y = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} y$$

$$y(0) = y_0 = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}, \quad \alpha, \beta \in [0, 1]$$

Picard Iteration:

- $y_{1,0} := y_0 = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$
- $y_{1,1}(t) = y_0 + \int_0^t B y_{1,0} d\tau = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} + \int_0^t \begin{pmatrix} b_{11}\alpha + b_{12}\beta \\ b_{21}\alpha + b_{22}\beta \end{pmatrix} d\tau = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} + tB \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$
- $y_{1,2}(t) = y_0 + \int_0^t B y_{1,1} d\tau = \left( I + tB + \frac{(tB)^2}{2} \right) \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$
- $y_{1,i}(t) = \sum_{\nu=0}^i \frac{(tB)^\nu}{\nu!} \begin{pmatrix} \alpha \\ \beta \end{pmatrix}, \quad i = 0, 1, \dots, k: \quad y_{1,k} = T y_0$

# Self Inclusion

Let  $I_0 := [0, 0]$ ,  $P_k(tB) := \sum_{\nu=0}^k \frac{(tB)^\nu}{\nu!}$ .

Determine  $\tilde{I}_1$  such that for some  $t = h$ :

$$y_0 + I_0 + \int_0^h B \left( P_k(\tau B) y_0 + I_0 + \tilde{I}_1 \right) d\tau \subseteq P_k(hB) y_0 + I_0 + \tilde{I}_1 = T y_0 + I_0 + \tilde{I}_1$$

and let  $I_1 := I_0 + \tilde{I}_1$ .

Iteration:  $y_j = T y_{j-1} + I_j, \quad j = 1, 2, \dots,$

that is

$$y_1 = T y_0 + I_1 = T c_0 + T C_0 x + I_1$$

and

$$y_j = T^j c_0 + T^j C_0 x + \sum_{i=1}^j T^{j-i} I_i.$$

# Naive Taylor Model Method without Shrink Wrapping

- $C_0 = 0$ : Point IVP  $y' = By, y(t_0) = y_0 = c_0$ :

Naive TM method without SW coincides with the direct method.

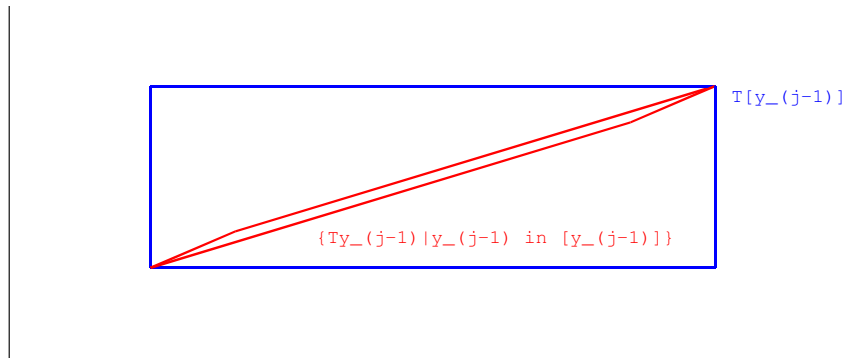
- $C_0 \neq 0$ :

Naive TM method without SW contains the same interval propagation of the local errors as the direct method.

In particular, after  $j$  steps we have

$$w(T(T(\dots TI_1)\dots)) = |T|^{j-1}w(I_1).$$

# Parallelepiped Method



$$\{Ty_{j-1} \mid y_{j-1} \in [y_{j-1}]\} \subseteq T[y_{j-1}]$$

Idea: Store  $\{Ty_{j-1} \mid y_{j-1} \in [y_{j-1}]\}$  instead of  $T[y_{j-1}]$ .

Let  $A_0 := I$ ,  $\hat{y}_0 := y_0$  and iterate:

$$\begin{aligned} s_j &:= m([z_j]), \quad \hat{y}_j := T\hat{y}_{j-1} + s_j \\ [y_j] &:= T\hat{y}_{j-1} + (TA_{j-1})[r_{j-1}] + [z_j] \\ [r_j] &:= (A_j^{-1}TA_{j-1})[r_{j-1}] + A_j^{-1}([z_j] - s_j) \end{aligned}$$

Parallelepiped method:

$$A_j := TA_{j-1} \Rightarrow [r_j] := [r_{j-1}] + A_j^{-1}([z_j] - s_j).$$

# Shrink Wrapping

Idea: Absorb the interval part of the TM into the polynomial part by increasing the polynomial coefficients.

Example: 
$$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} + \begin{pmatrix} [-1, 1] \\ [1, 5] \end{pmatrix} \mid \alpha, \beta \in [-1, 1] \right\}$$
$$= \left\{ \begin{pmatrix} 1 \\ 3 \end{pmatrix} + \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \mid \alpha, \beta \in [-1, 1] \right\} = \begin{pmatrix} [-2, 4] \\ [0, 6] \end{pmatrix}$$

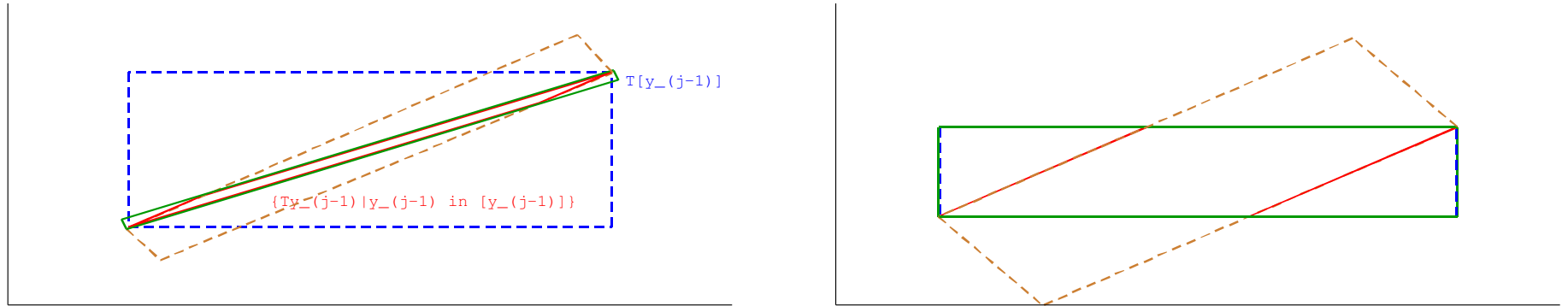
Shrink wrapping for ODE  $y' = By$ :

$$d_j := w \left( (T^j C_{j-1})^{-1} I_j \right) / 2,$$
$$C_j := (1 + d_j) C_{j-1}, \quad I_j := 0.$$

Thus, we obtain

$$y_j = T^j c_0 + \prod_{i=1}^j (1 + d_i) C_0 x.$$

# QR Method



Idea: Stabilize the iteration by orthogonalization

QR method:  $T A_{j-1} P_j = Q_j R_j, \quad A_j := Q_j$

# Preconditioning

Unconditioned TM: Flow of the ODE at  $t = t_0$  is represented by a single TM:

$$y(t_0) = c_0 + C_0 x = P_0 + I_0,$$

where

- $c_0$ :  $n$ -vector,
- $C_0$ :  $(n, n)$ -diagonal matrix,
- $x$ : Symbolic  $n$ -vector with components  $x_i \in [-1, 1]$ ,
- $P_0 = c_0 + C_0 x$ : Multivariate polynomial (of order 1),
- $I_0$ : Zero interval.

Similar at  $t = t_j$ :

$$y(t_j) = c_j + C_j x + I_j = P_j + I_j$$

(linear ODE, hence linear set in  $x$  for all  $t$ ).

# Preconditioning

Preconditioned TM: Flow of the ODE at  $t = t_j$  is represented by a concatenation of two TMs (and a scaling matrix  $S_j$ ):

$$\begin{aligned} y(t_j) &= (P_{j,l} + I_{j,l}) \circ S_j \circ (P_{j,r} + I_{j,r}) \\ &= (c_{j,l} + C_{j,l} x + I_{j,l}) \circ S_j \circ (c_{j,r} + C_{j,r} x + I_{j,r}) \end{aligned}$$

**Theorem:** Integrating the flow of the ODE only acts on the left TM.

“Proof”: If

$$\int f(x, t) dt = F(x, t) \quad \text{and} \quad x = g(u),$$

then

$$\int f(g(u), t) dt = F(g(u), t).$$

# Preconditioning

Preconditioning for linear ODEs: Flow at  $t = t_j$ :

$$y(t_j) = (c_{j,l} + C_{j,l} x + I_{j,l}) \circ S_j \circ (P_{j,r} + I_{j,r})$$

Flow after integration:

$$\begin{aligned} y(t_{j+1}) &= (Tc_{j,l} + TC_{j,l} x + I_{j+1,l}) \circ S_j \circ (P_{j,r} + I_{j,r}) \\ &= (Tc_{j,l} + C_{j+1,l} x + [0, 0]) \\ &\quad \circ \left\{ \left[ C_{j+1,l}^{-1} TC_{j,l} x + C_{j+1,l}^{-1} I_{j+1,l} \right] \circ S_j \circ (P_{j,r} + I_{j,r}) \right\} \\ &= (c_{j+1,l} + C_{j+1,l} x + [0, 0]) \circ S_{j+1} \circ (P_{j+1,r} + I_{j+1,r}) \end{aligned}$$

The expression in brackets is the same as in the PE and QR interval iteration.

# Preconditioning

Expression in brackets:

$$\begin{aligned} & \left[ C_{j+1,l}^{-1} T C_{j,l} x + C_{j+1,l}^{-1} I_{j+1,l} \right] \circ S_j \circ (c_{j,r} + C_{j,r} x + I_{j,r}) \\ &= C_{j+1,l}^{-1} T C_{j,l} S_j c_{j,r} + C_{j+1,l}^{-1} T C_{j,l} S_j C_{j,r} x + C_{j+1,l}^{-1} T C_{j,l} S_j I_{j,r} + C_{j+1,l}^{-1} I_{j+1,l} \\ &= S_{j+1} \circ (S_{j+1}^{-1} C_{j+1,l}^{-1} T C_{j,l} S_j c_{j,r} + S_{j+1}^{-1} C_{j+1,l}^{-1} T C_{j,l} S_j C_{j,r} x \\ &\quad + S_{j+1}^{-1} (C_{j+1,l}^{-1} T C_{j,l} S_j I_{j,r} + C_{j+1,l}^{-1} I_{j+1,l})) \\ &= S_{j+1} \circ (c_{j+1,r} + C_{j+1,r} x + I_{j+1,r}) = S_{j+1} \circ (P_{j+1,r} + I_{j+1,r}) \end{aligned}$$

If  $S_j = I$  for all  $j$ , then the symbolic part and the interval part propagate like the interval part in the PE and QR interval methods.

# Preconditioning without $S_j$ -matrices

Expression in brackets:

$$\begin{aligned} & \left[ C_{j+1,l}^{-1} T C_{j,l} x + C_{j+1,l}^{-1} I_{j+1,l} \right] \circ (c_{j,r} + C_{j,r} x + I_{j,r}) \\ &= C_{j+1,l}^{-1} T C_{j,l} c_{j,r} + C_{j+1,l}^{-1} T C_{j,l} C_{j,r} x + C_{j+1,l}^{-1} T C_{j,l} I_{j,r} + C_{j+1,l}^{-1} I_{j+1,l} \\ &= c_{j+1,r} + C_{j+1,r} x + I_{j+1,r} = P_{j+1,r} + I_{j+1,r} \end{aligned}$$

The symbolic part and the interval part propagate like the interval part in the PE and QR interval methods.

# Linear Example 1: Pure Contraction

$$B = \begin{pmatrix} -0.6875 & -0.1875 & 0.08838834762 \\ -0.1875 & -0.6875 & 0.08838834762 \\ 0.08838834762 & 0.08838834762 & -0.875 \end{pmatrix} \approx \begin{pmatrix} -\frac{1}{2} & 0 & 0 \\ 0 & -\frac{3}{4} & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

	$t$	Steps	Accuracy	Time
AWA pe	75.5	463	1.4E+4	$M^{-1}$ failed;
AWA ivpe	74.5	479	6.3E-15	$M^{-1}$ failed;
AWA QR	1000	6611	5.4E-15	10.5
TM na	100	9428	2.5E+31	573
TM SW	60.4	4423	Failed	—
TM PR	100	572	1.6E-12	62

(Orders: AWA 20, TM 18)

## Linear Example 2: Pure Rotation

$$B = \begin{pmatrix} 0 & -0.7071067810 & -0.5 \\ 0.7071067810 & 0 & 0.5 \\ 0.5 & -0.5 & 0 \end{pmatrix} \approx \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

	$t$	Steps	Accuracy	Time
AWA pe	1000	1925	3.2E-10	2.7
AWA QR	1000	1925	3.2E-10	2.8
TM na	100	9523	6.3E+36	583
TM SW	100	7582	(as PR)	467
TM PR	100	7582	2.2E-8	517

## Linear Example 3: Contraction and Rotation

$$B = \begin{pmatrix} -0.125 & -0.8321067810 & -0.3232233048 \\ 0.5821067810 & -0.125 & 0.6767766952 \\ 0.6767766952 & -0.3232233048 & -0.25 \end{pmatrix} \approx \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{pmatrix}$$

	$t$	Steps	Accuracy	Time
AWA pe	78	218	5.0E+17	Integration failed
AWA ivpe	118	313	1.1E+17	Integration failed
AWA QR	1000	2683	3.9E-10	4.3
TM na	100	9599	9.1E+44	585
TM SW	100	7742	1.2E+107	485
TM PR	100	7741	1.8E-8	530